

NDACC and Water Vapor Raman Lidars

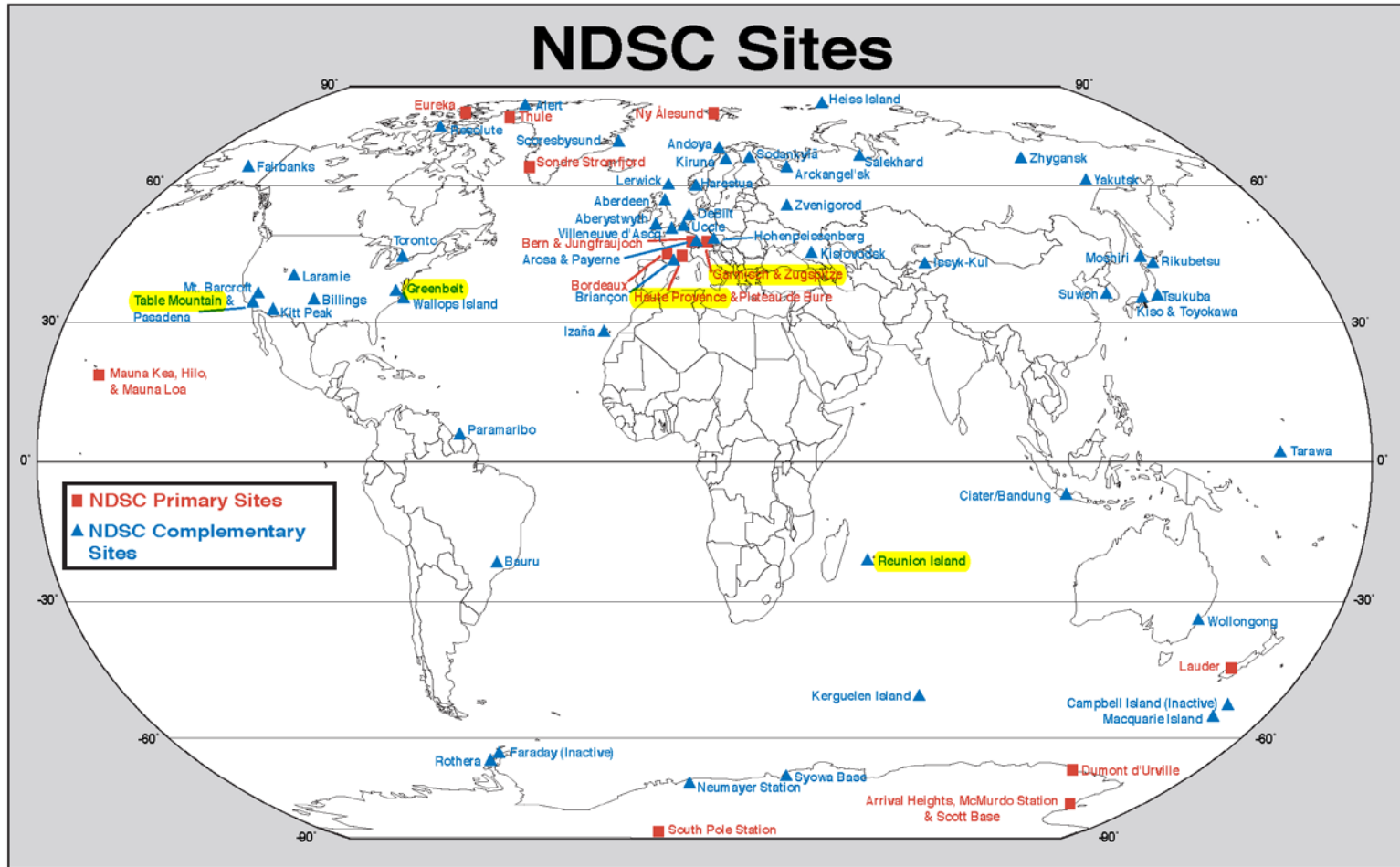
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NDACC and Water Vapor Raman Lidar 1. Measuring goals

- Water vapor plays significant role in radiative balance of the UTLS
- Water Vapor variability is very high in both space and time
- High resolution water vapor measurements in the UTLS has remained sparse until today
- **→ 2002: It was proposed to add water vapor Raman lidars to the set of NDACC instruments with the specific following requirements:**
 - Capable of measuring water vapor near and above the tropopause
 - Capable of measuring down to a few ppm
 - Capable to sustain relatively high vertical and temporal resolution



NDACC and Water Vapor Raman Lidar: 3. Technique/retrieval

- Vibrational Raman backscatter technique at two wavelengths
- UV:
 - Laser emission at 355 nm
 - Reception at 387 nm (Raman N₂) and 407.5 nm (H₂O)
- Visible:
 - Laser emission at 532 nm
 - Reception at 607 nm (Raman N₂) and 660 nm (H₂O)
- Lidar signals corrected for background noise, saturation/pile-up effects, signal induced noise, range, Rayleigh extinction.
- Small additional correction due to temperature dependence of the H₂O cross-section is needed occasionally if using very narrow filter
- After correction, the ratio of the lidar signals at the two wavelengths is **proportional** to water vapor mixing ratio.

→ Needs calibration !

NDACC and Water Vapor Raman Lidar: 4. Calibration

- Calibration techniques:
 - **Internal/theoretical:** Very challenging because requires accurate knowledge of transmission ratios of **ALL** the lidar optical and electro-phonic components
 - virtually impossible to achieve at required accuracy
 - **Semi-empirical:** Use of a Calibration lamp to illuminate lidar receiver in conditions that mimic real measurements: Difficult, but possible
 - Accuracy depends mostly of lamp calibration accuracy
 - **External:** Use of independent measurements, e.g., radiosonde, microwave
 - Easy to implement but accuracy limited by that of independent measurement

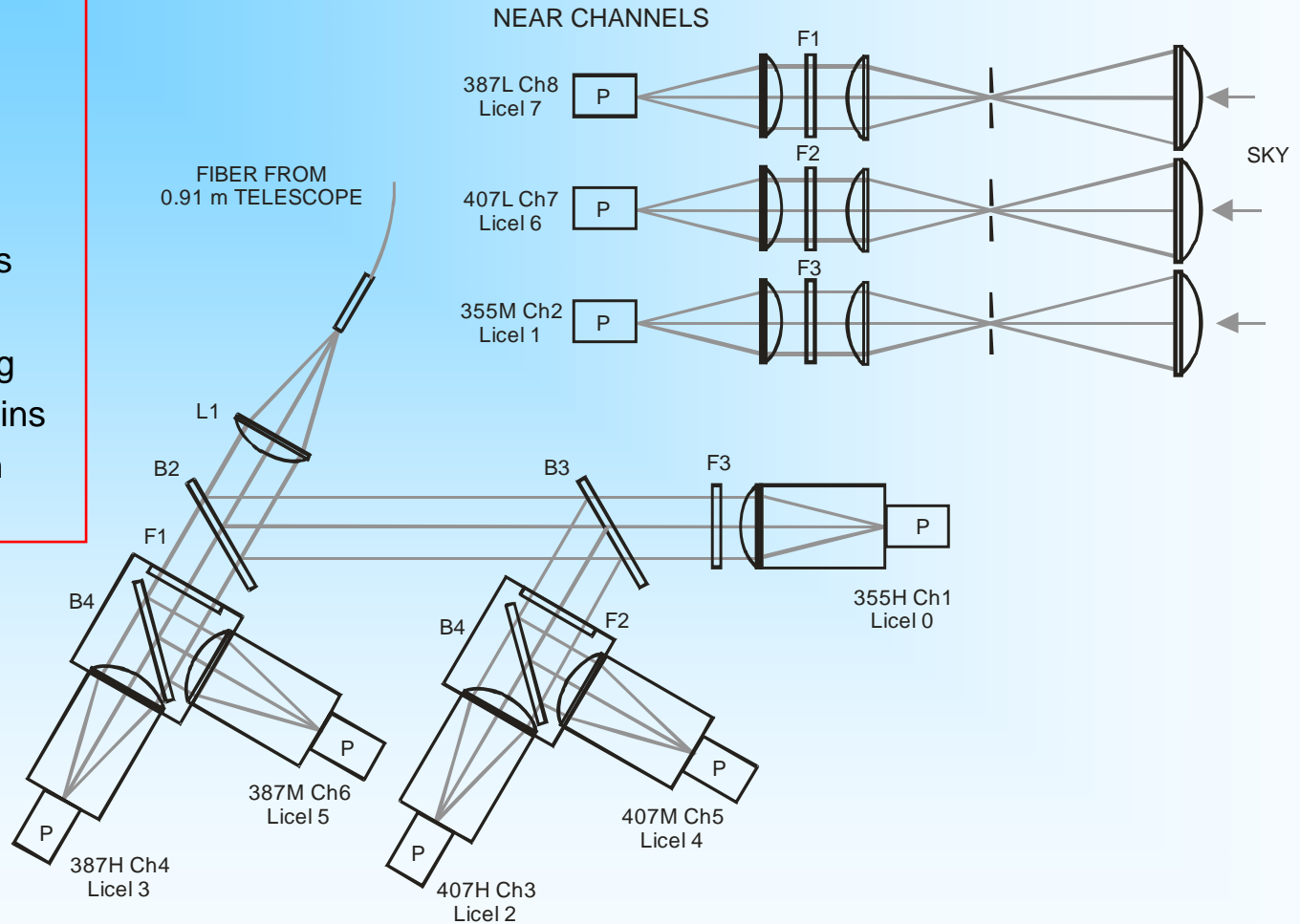
**Important requirements for NDACC long-term measurements
and associated challenges to lidar community:**

1. **High capability lidar**
 - ➔ **Capable of detecting a few ppm at tropopause**

2. **Stable calibration constant**
 - ➔ **Simultaneous multiple calibration techniques must be available to cross-validate calibration constants from each technique, and insure long-term stability**

The Raman Lidar at Table Mountain Facility: Overview 1

Laser energy:
 700 mJ/pulse
 8 channels:
 3 w.v. ranges
 3 telescopes:
 One 90 cm
 Three 6 cm
 Hamamatsu PMTs
 Licel
 photocounting
 8000 7.5-m bins
 Vertical resolution
 75-m



The Raman Lidar at Table Mountain Facility: Overview 2

- Calibration used so far:
 - Radiosondes: Vaisala Humicap RS-92 sensors
- Future plans:
 - UV lamp, GPS, Microwave
 - Simultaneous, multiple calibration techniques
- Important requirement for NDACC long-term measurements:
 - Stable calibration constant

The Raman Lidar at Table Mountain Facility: Overview 3

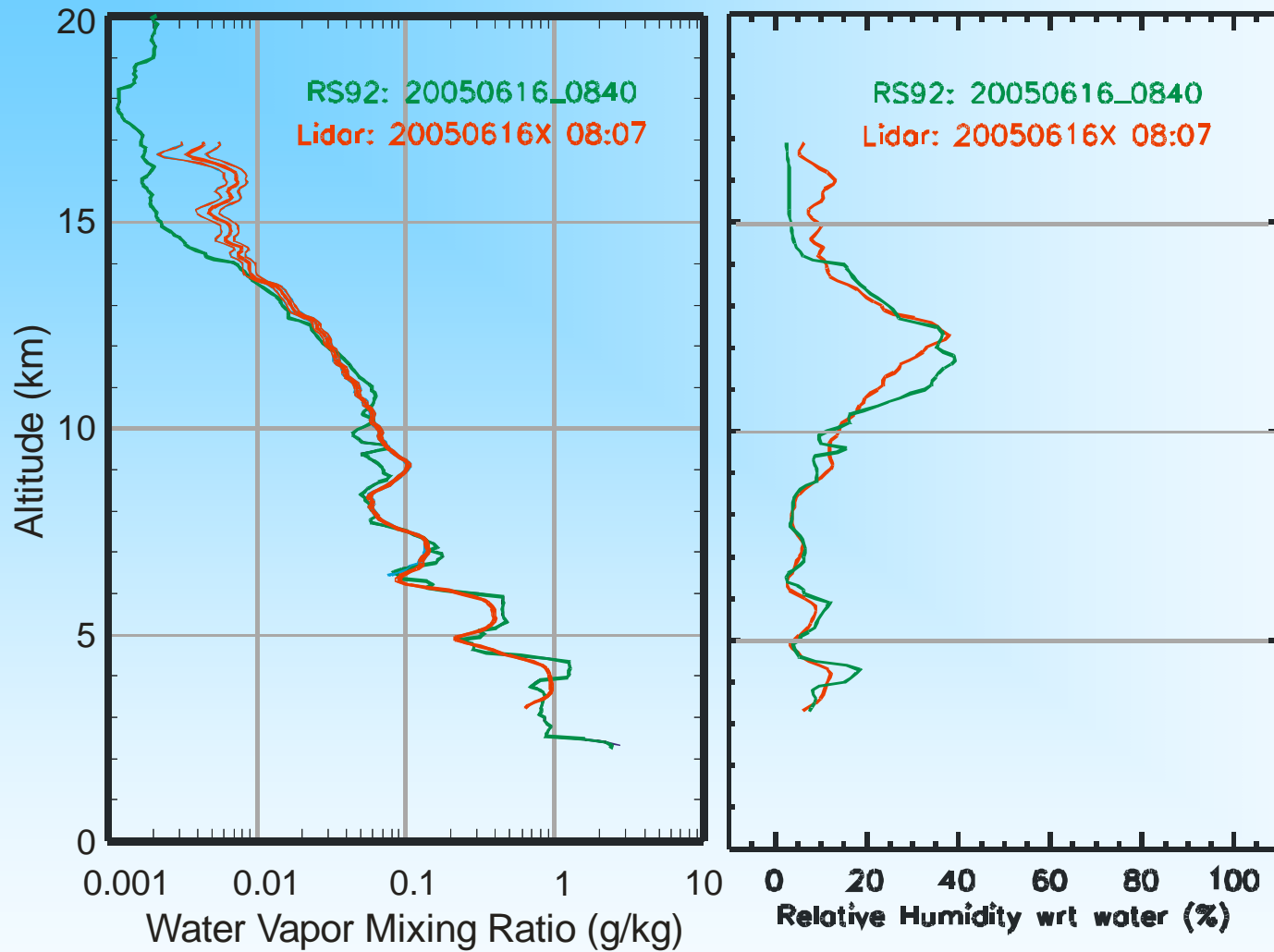
TMF

- 50 miles NE of Los Angeles
- Lat: 34.4°N
- Long: 117.7°W
- Alt: 2285 m (7500 ft)
– > 340 clear nights/year

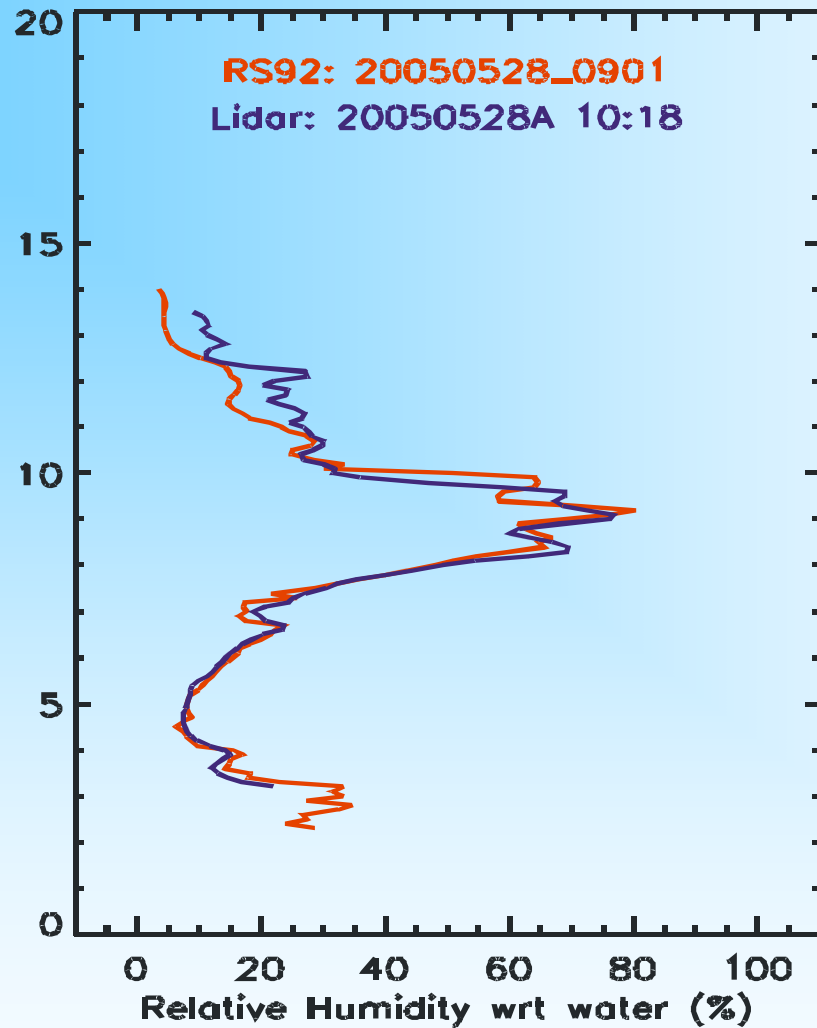
Dataset

- TMF water vapor measurement program started in late 2004
- **November 2004 – Present:**
 - Radiosonde P,T, (2.3-20 km), RH (2.3-15 km)
- **April 2005 – Present:**
 - Raman Lidar (4-19 km)
- **Lidar vertical resolution and accuracy:**
 - 75 m instrumental, 2-h routine integration (5-minutes minimum)
 - WV total error estimated to ~5-8 ppm at tropopause

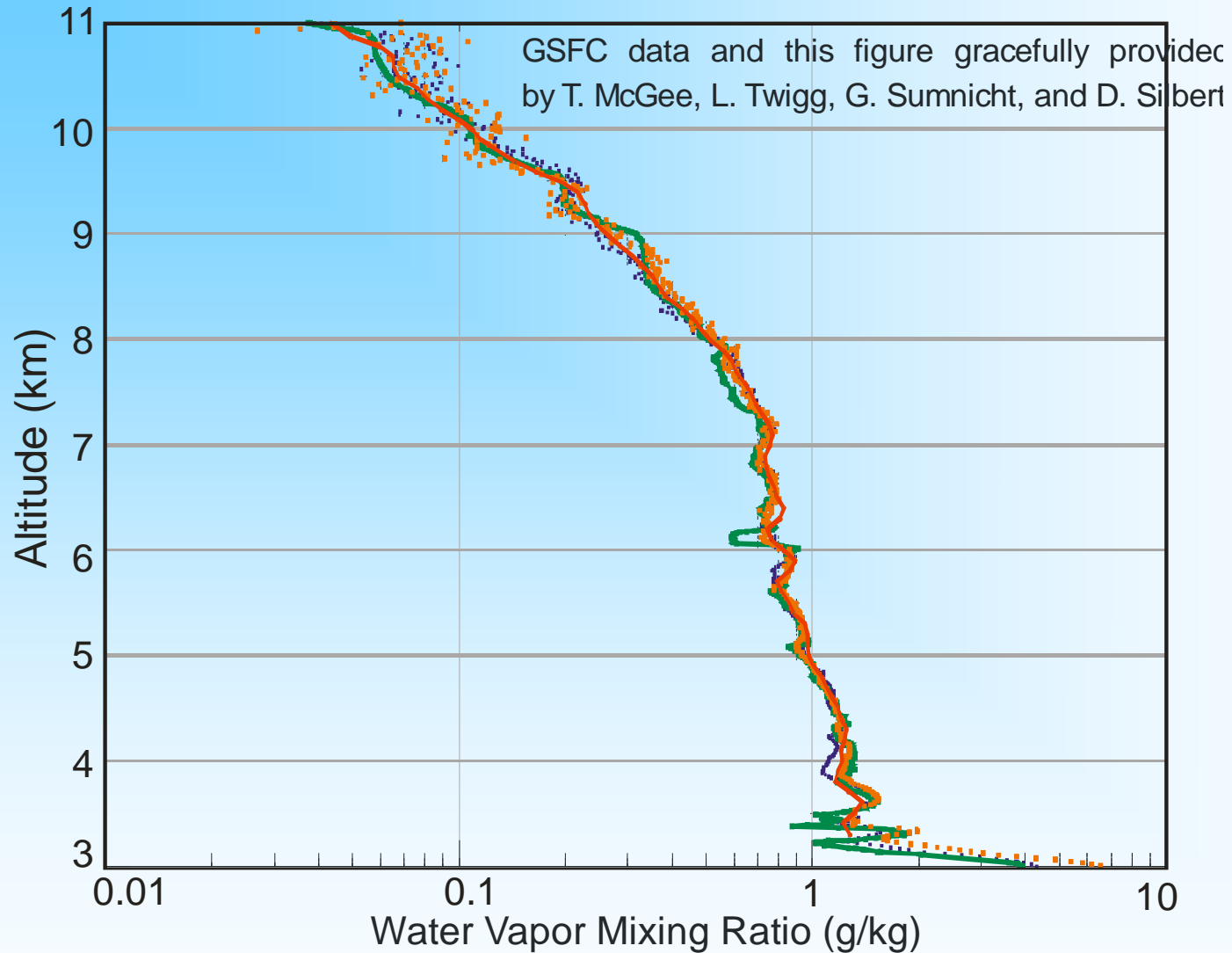
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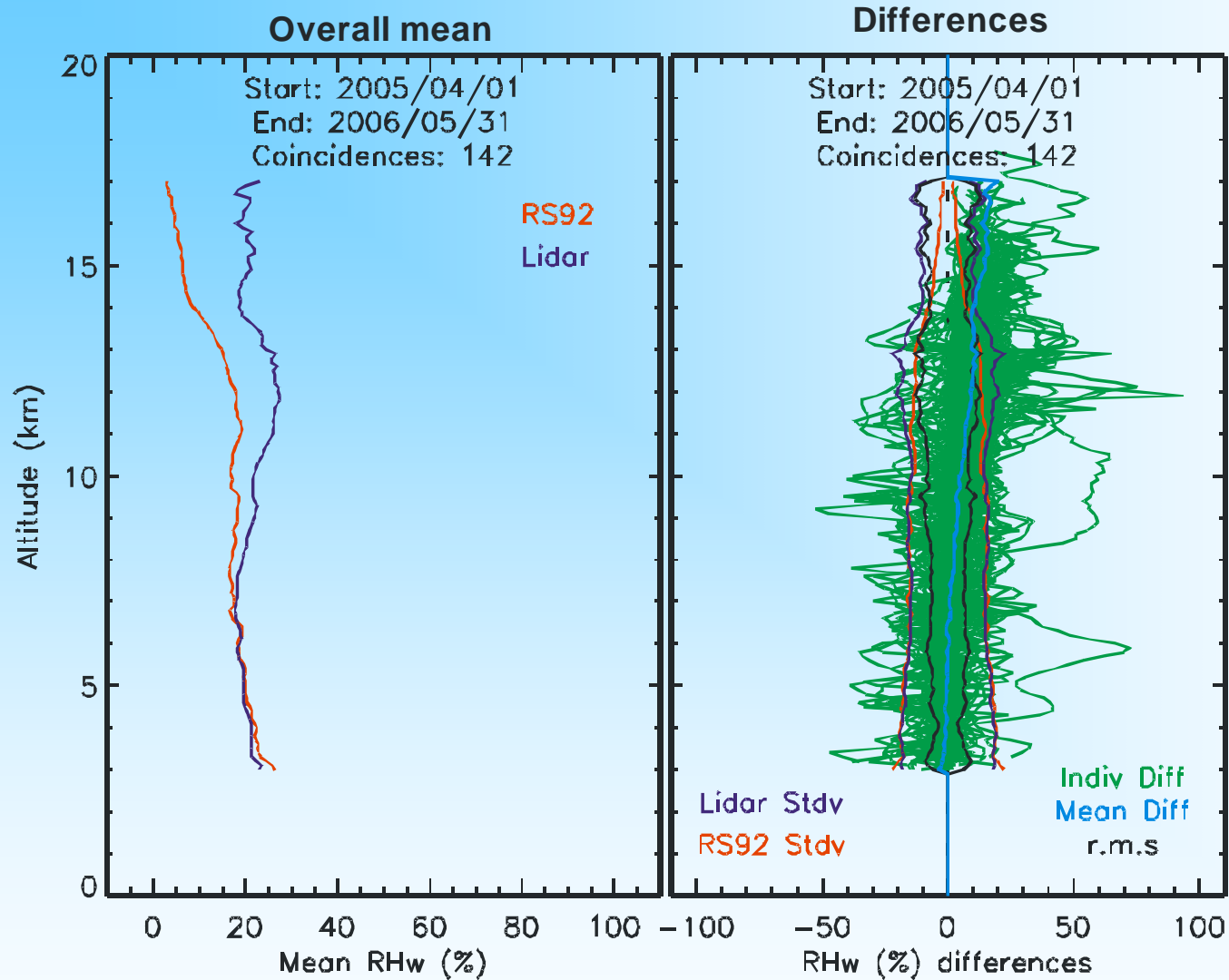
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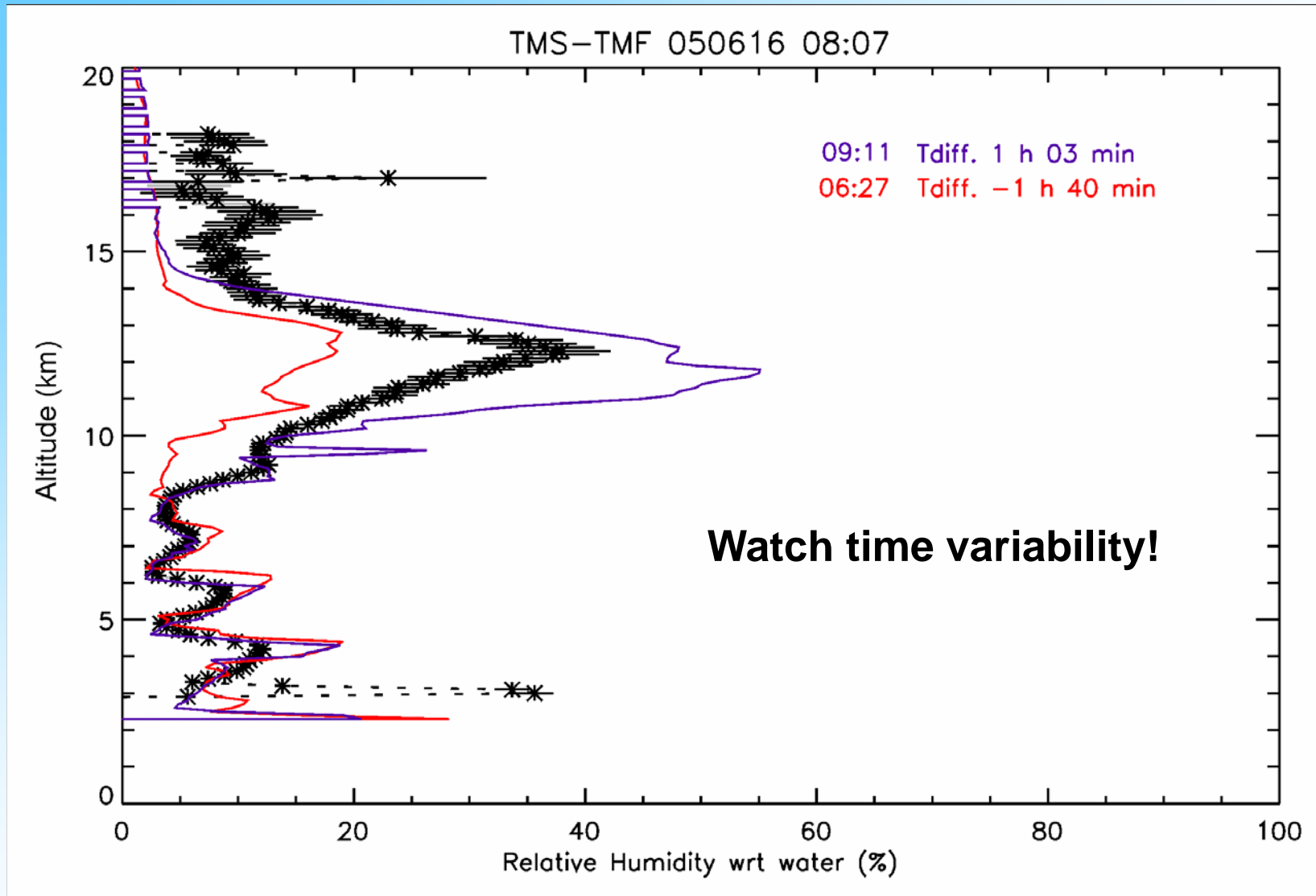
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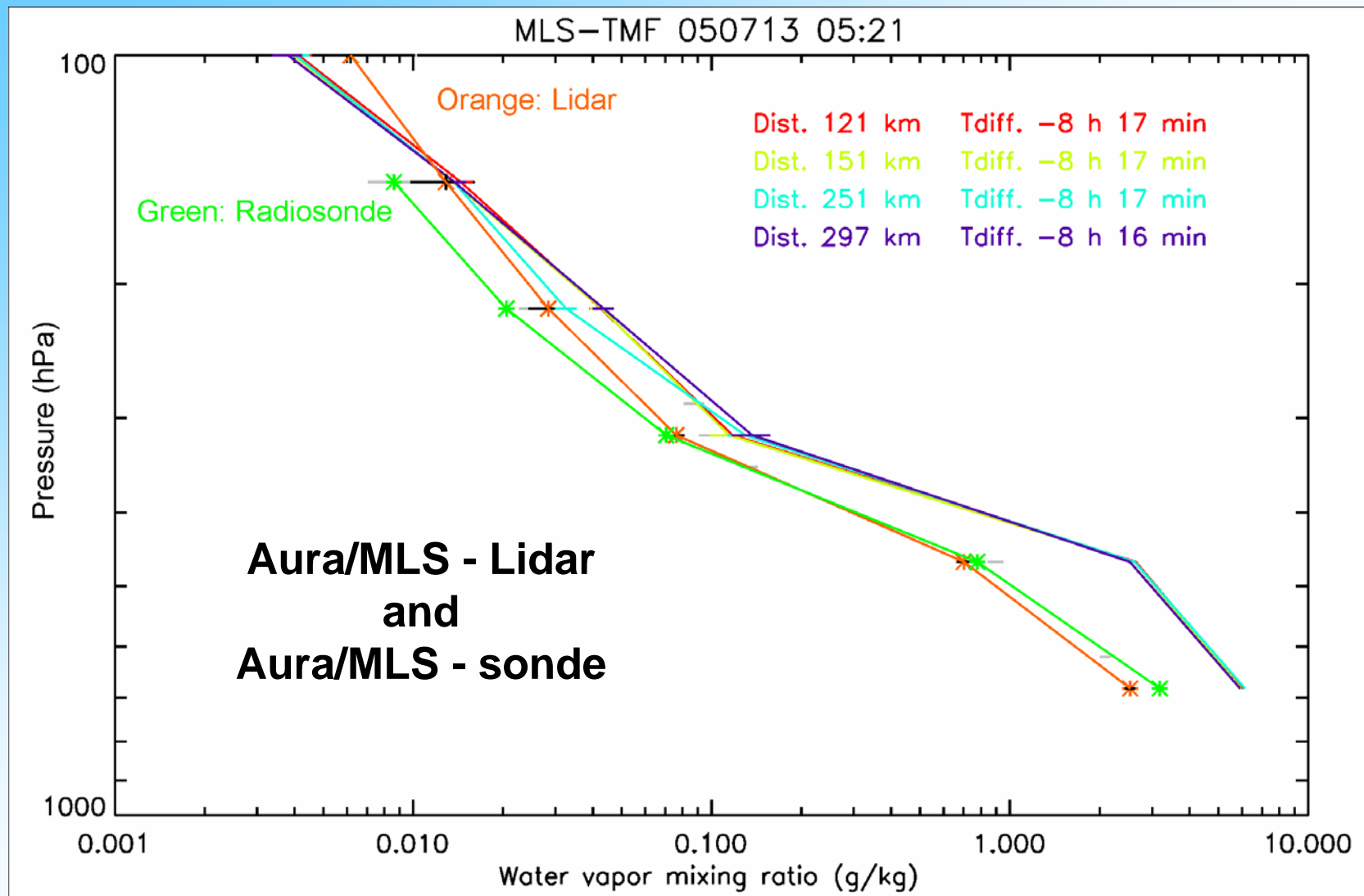
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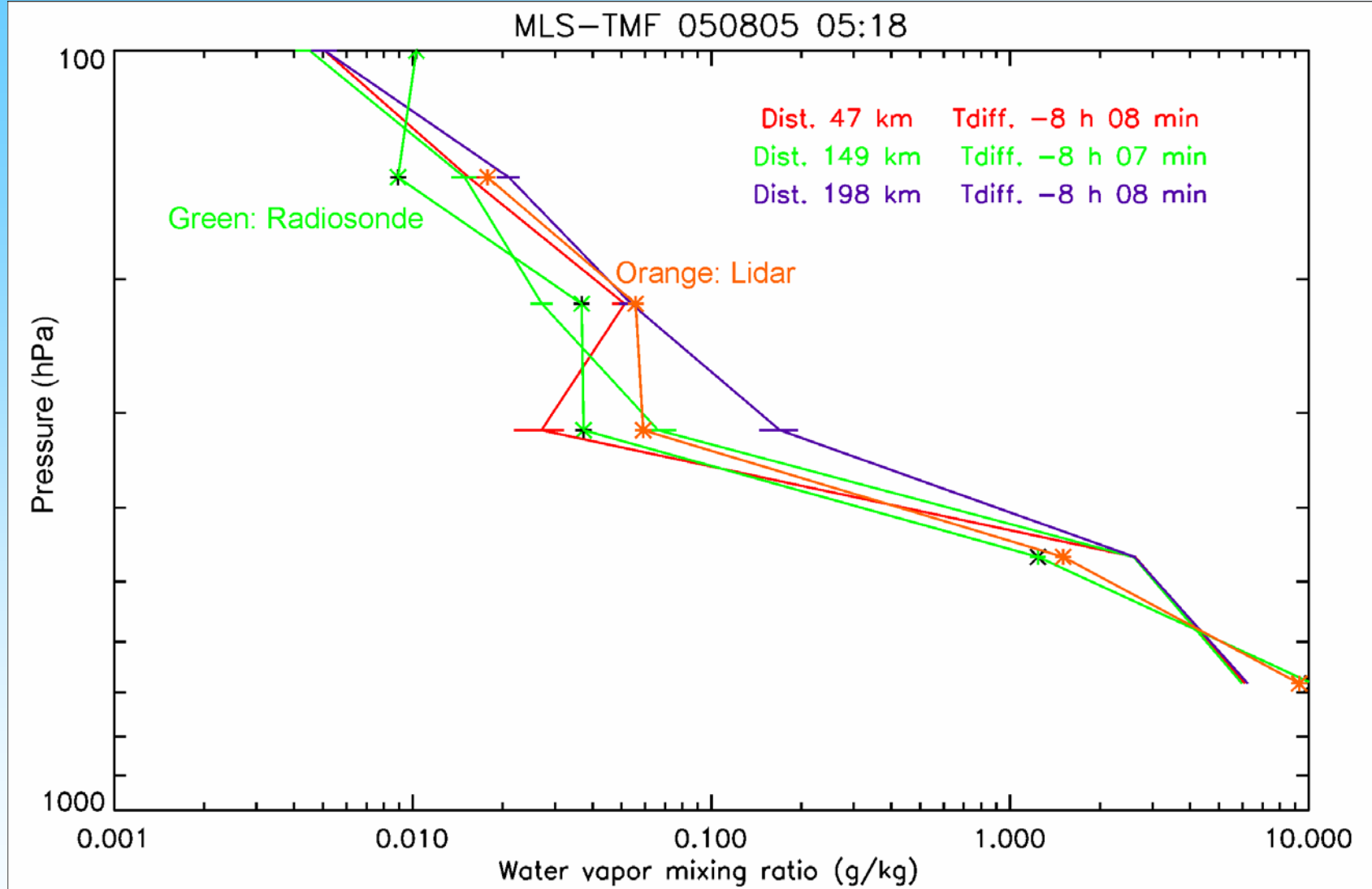
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The Raman Lidar at Table Mountain Facility: Overview 9



The Raman Lidar at Table Mountain Facility: Overview 10



The Raman Lidar at Table Mountain Facility: Summary

- So Far:

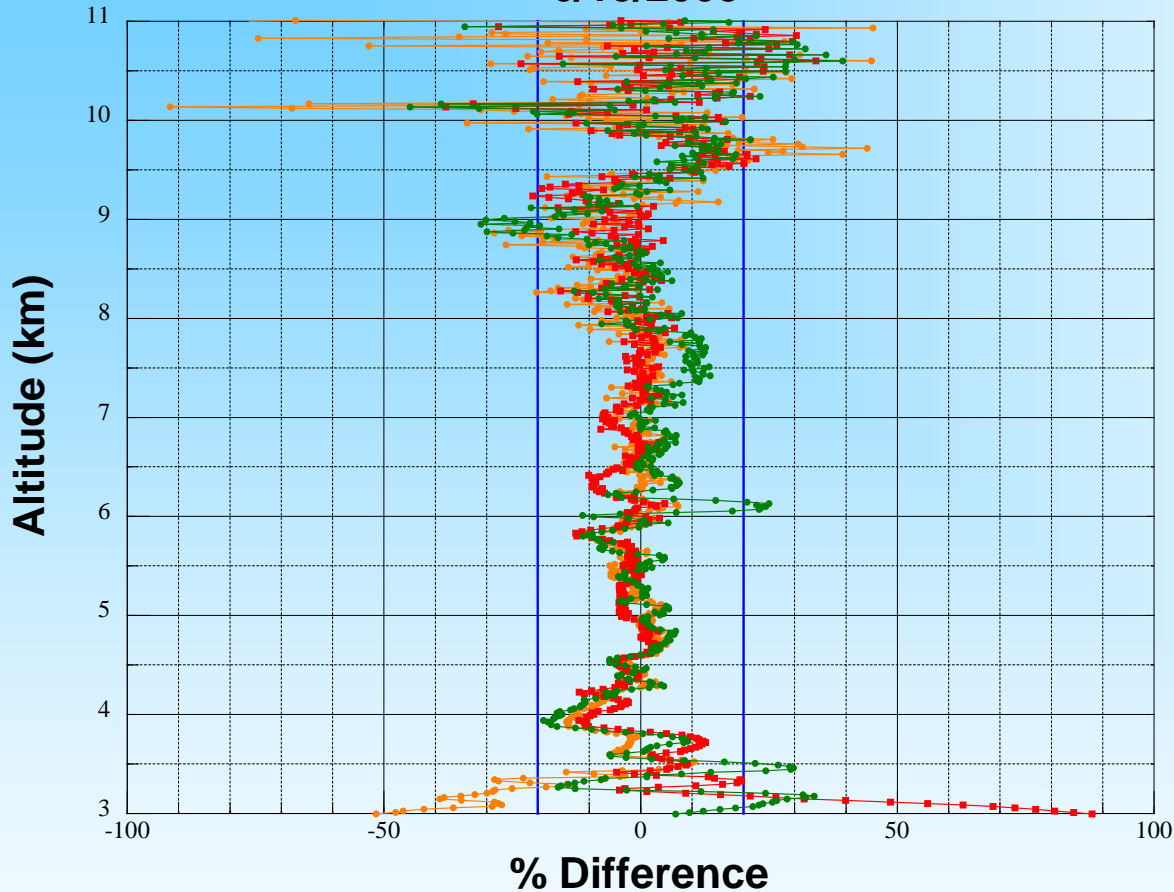
- TMF Water Vapor Raman Lidar is doing well
- Capable to reach 15-18 km for a 2-hour integration
- As of today, used only radiosonde for calibration

- Next:

- Introduce new calibration techniques:
 - Lamp
 - GPS?
 - Microwave?
- Improve lidar power/aperture capability to reach final objectives of detection level of 2 ppm at 15 km

The Raman Lidar at Table Mountain Facility: Overview 1

6/13/2005



6/13/2005

Red = JPL-AT

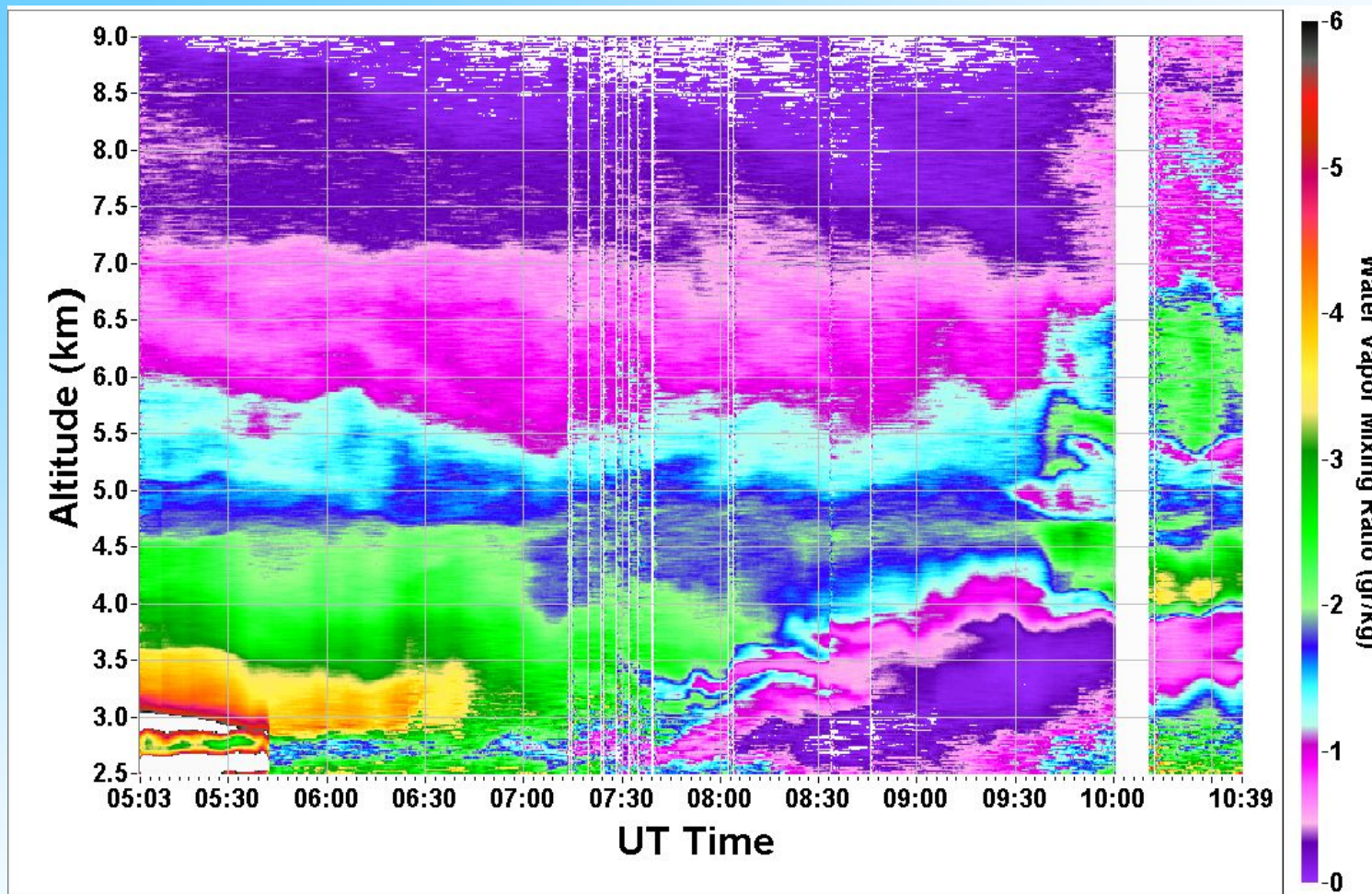
Green = Sonde-AT

Orange = STROZ-Lite - AT

From:

Tom McGee and Larry
Twigg, NASA-GSFC

The GSFC Raman Lidars: Overview 2



From: Tom McGee and Larry Twigg, NASA-GSFC